

Human Systems Engineering for Launch Processing at Kennedy Space Center (KSC)

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Abstract

Launch processing at Kennedy Space Center (KSC) is primarily accomplished by human's users of expensive and specialized equipment. In order to reduce the likelihood of human error, to reduce personal injuries, damage to hardware, and loss of mission, the design process for the hardware needs to include the human's relationship with the hardware. Just as there is electrical, mechanical, and fluids, the human aspect is just as important. The focus of this presentation is to illustrate how KSC accomplishes the inclusion of the human aspect in the design using human centered hardware modeling and engineering. The presentations also explains the current and future plans for research and development for improving our human factors analysis tools and processes.

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KSC Human Factors



Darcy Miller



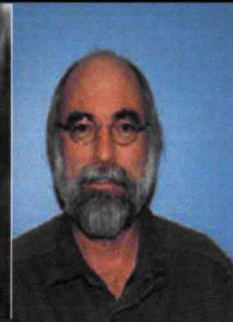
Tim Barth
Ph.D.



Donald Tran



Lori Gregg



Brad Lawrence

HFEAT

Human/System Interface

Issues

Requirement (Source, Title, Sub
Section, and requirement words)

[illegible]

HFEAT

Conditions

Consequences

Type of processing, Assembly, Nominal, inspection, Emergency, etc.

04 Designed Equipment for Maintenance

This type of design should make equipment maintenance easy, fast, and safe. The system maintenance concept also affects equipment design. For example, is a particular unit of equipment intended to be repaired on site? Is it intended to be removed and repaired at another location? Is it intended to be disassembled and replaced with another unit? A third factor affecting equipment design is the physical environment in which it will be located, will it be exposed to weather or to temperature extremes? Will the user be wearing gloves or other protective clothing? Finally, equipment must accommodate characteristics of the user themselves. Here

1. Use Task	2. Use Device Type	3. Use Sub-Section Title	4. Equipment	5. Conditions	6. Consequences	7. To select put an "X" in the box	8. Is Colored? (Y/N)	9. Primary Verification	10. Priority Rank Circumstances	11. Priority Rank Checklist	12. Priority Rank Product	13. Why How Complaint	14. Potential Remediation Actions	15. Notes
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04 Design for Maintenance

HFEAT

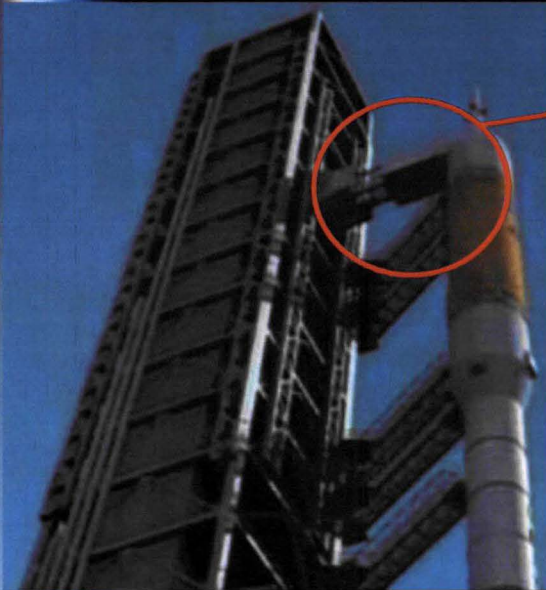
Requirement Satisfied, Verification, Consequence, Likelihood, Priority Rank, Why Non-Compliant, Recommendation, Notes.

[illegible]

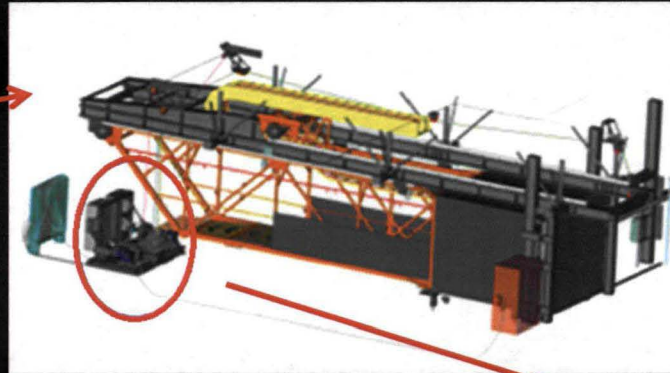
Each Tab is a FAA Chapter: Design equipment for maintenance, Controls and visual indicators, etc.

Example Actuator Motor

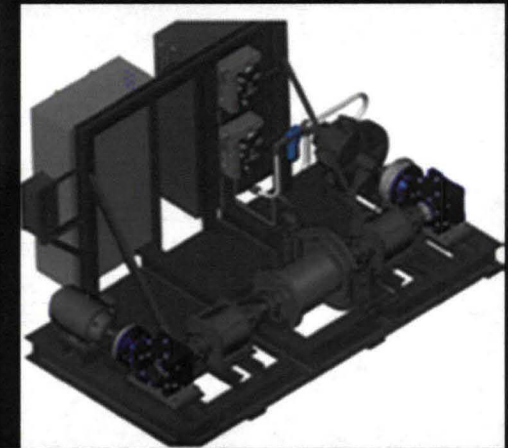
Mobile Launcher



Crew Access Arm



Actuator Motor



Actuator motor

Complete visual and physical access

Access for maintenance

Move the motor

[illegible]

KSC Human Engineering Modeling and Performance Laboratory (HEMAP)

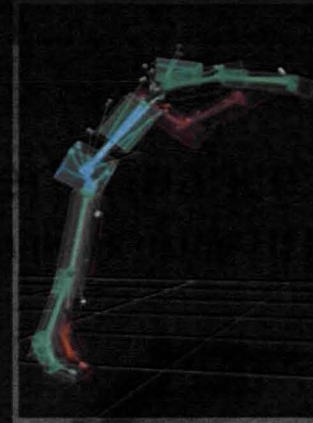
Human Systems Engineering Analysis using HEMAP



Real Task



**Motion Captured Task
(Actual Techs &
Biomechanical Data)**



**Real time
Biomechanical
Model**




**CAD and Human
Real time
Simulations**

A Baseline simulation of the existing process was created.

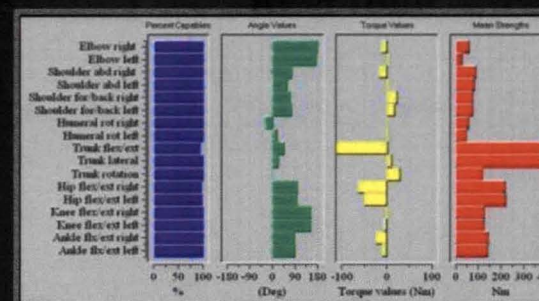
The Task Analysis Toolkit within Transom Jack was used to address the concerns of worker fatigue, recovery time, lower back stress and optimal performance.

The ergonomics, Jack evaluation resulted in identified high levels of stress on: Musculoskeletal system (trunk flex and trunk lateral) and elbow, knees, ankles, hip, shoulder, and torso. Low back showed high-compression spine forces, exceeding the National Institute for Occupational Safety and Health (NIOSH) back compression limit. Weight was far forward of the worker.

Recommendations include assessing a new configuration that would promote an improved posture for each worker such as height-adjustable stands, wider work surface for two workers, and means to get stand closer to installation area.



**Human Factors Analyses and
Recommendations**

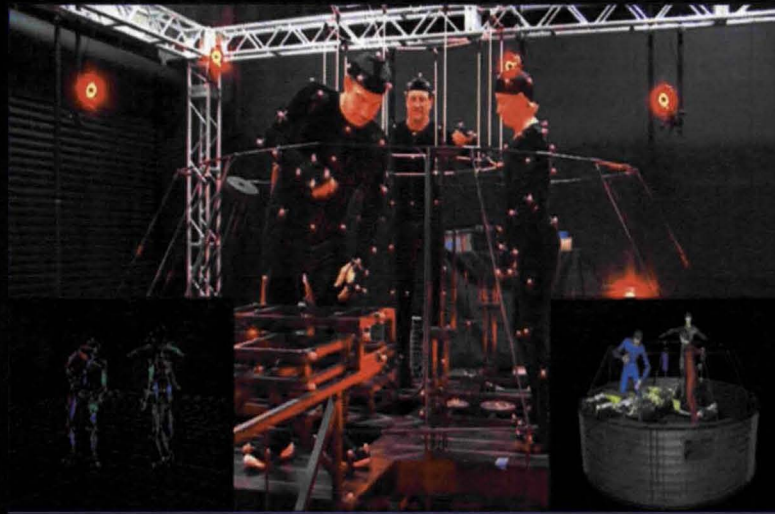


**Real time Ergonomic
Analysis**

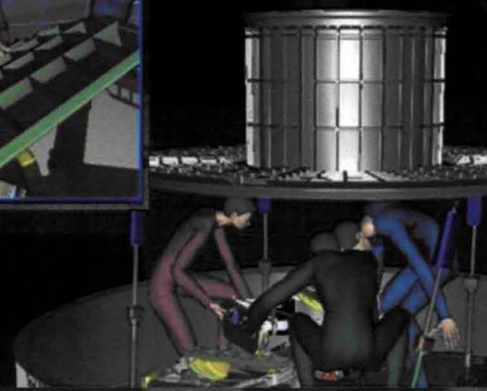
HEMAP supports multiple person/object tracking into live ergonomic analyses

Requirements Compliance through Motion Capture Human Factors Analysis for Proactive Design and Operational Improvements

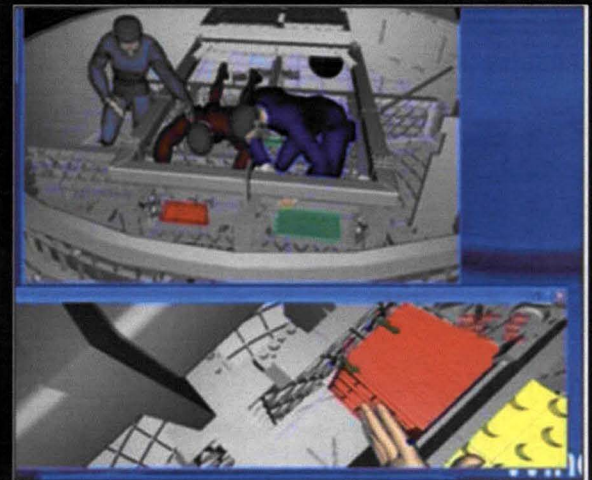
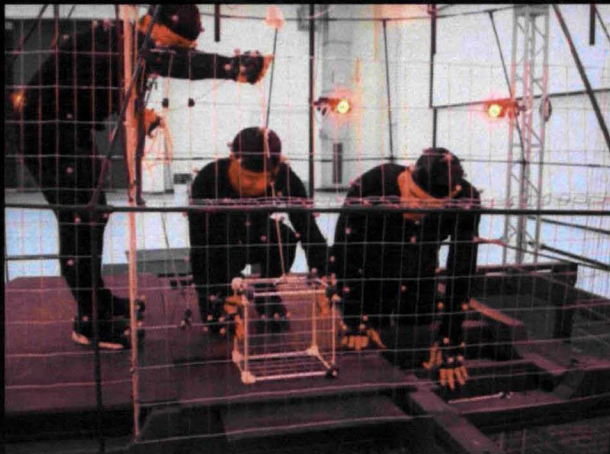
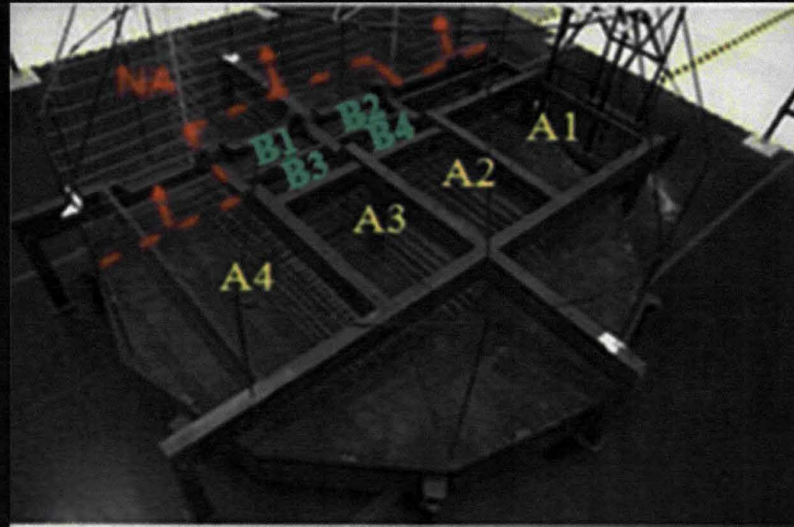
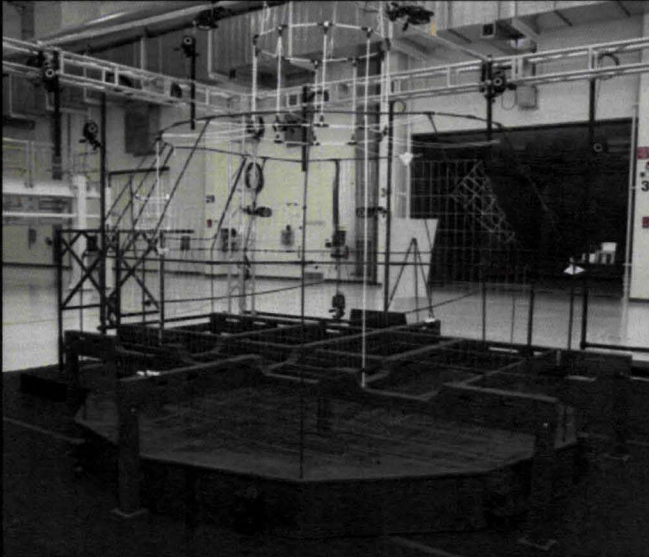
Motion Capture



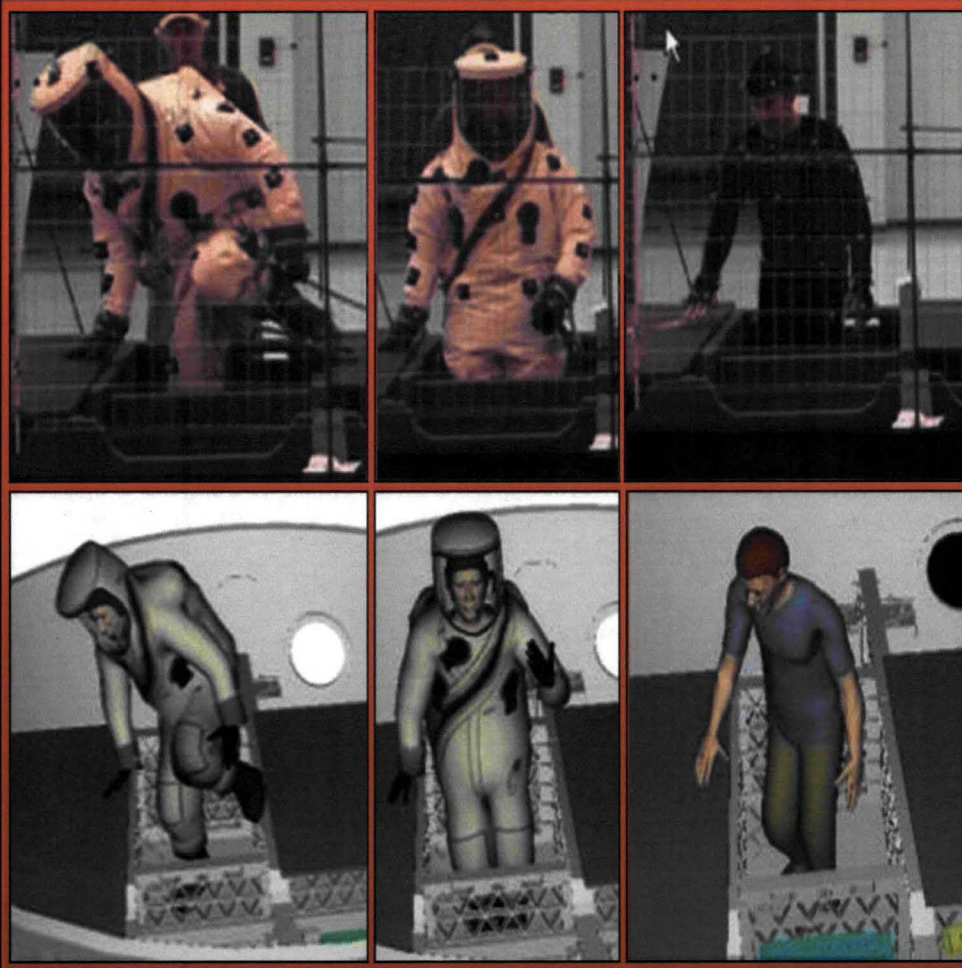
CAD Models with Human Models



Orion Avionics Box Installation



Self-Contained Atmospheric Protective Ensemble SCAPE Suit



Markers placed on
SCAPE suits to create
actual life size and
motion of suits

Interactive Virtual collaboration

- Interactive virtual collaboration of motion capture data among KSC and MSFC
 - The web sharing of motion capture tasks within the shared virtual environment provides real-time ability to update designs based on actual human-system interfaces being evaluated.



Motion Capture at KSC



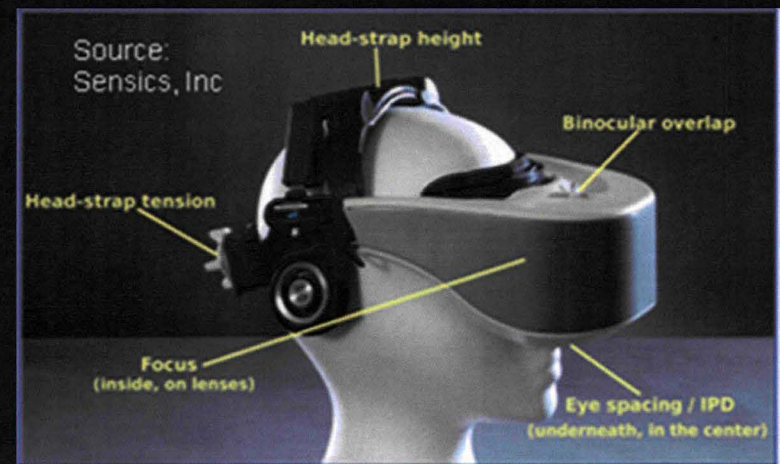
Combined Design Environment



Motion Capture at MSFC

Head-Mounted Displays

- Incorporation of wearable Head-Mounted Displays (HMDs):
 - Negates need for physical mockups.
 - Familiarization/training benefits
 - Collaborative web sharing of models and live motion tracking among NASA centers
 - Immersing the HMD wearers in simple physical mockups



National Aeronautics and
Space Administration



Kennedy Space Center **Future Development Concept**

"A new way of doing business for a new generation of explorers"

2012-2031

Kennedy Space Center

Future Development Concept

Goal 1: Ensure mission success by enabling Government and commercial access to space

Goal 2: Develop, operate, and sustain a robust launch and payload processing complex for all providers

Goal 3: Conduct research and develop technology (R&T) representative of KSC expertise to enable NASA mission success

Goal 4: Provide a flexible, cost-effective institution to enable success

Goal 5: Inspire, engage, and educate through enriching programs, internships, and partnerships

Goal 1: Ensure mission success by enabling Government and commercial access to space

- a. Assure successful Government access to space
- b. Enable development of routine commercial access to space

Goal 2: Develop, operate, and sustain a robust launch and payload processing complex for all providers

- a. Convert the KSC launch and payload processing complex into a multi-user capability
- b. Establish plans, processes, and agreements to support multi-user activity

Goal 3: Conduct research and develop technology (R&T) representative of KSC expertise to enable NASA mission success

- a. Advance KSC's R&T into relevant uses for KSC, NASA, and the Nation
- b. Conduct R&T development to enhance NASA capabilities to explore
- c. Perform R&T to enhance surface and launch systems for any

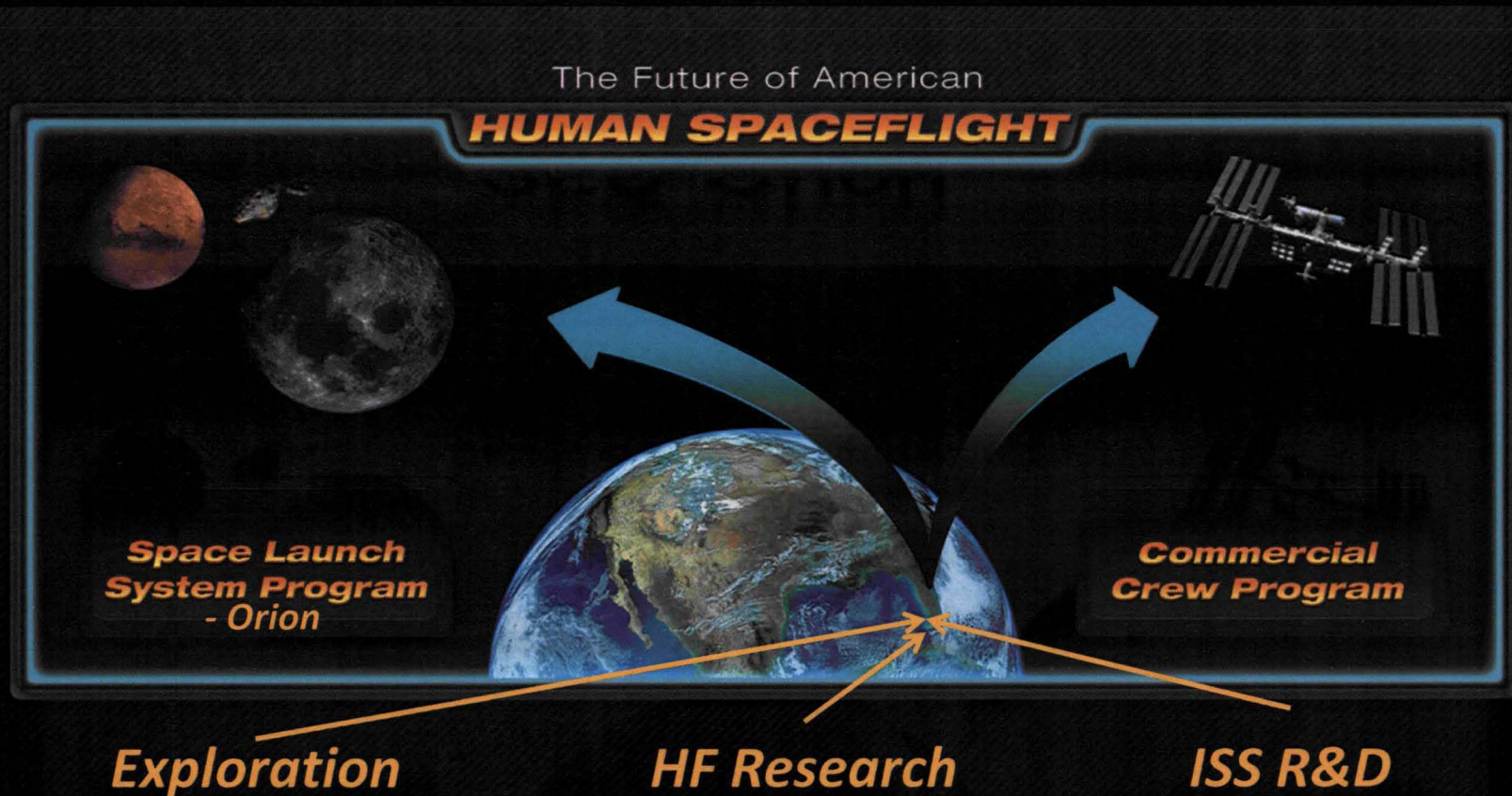
Goal 4: Provide a flexible, cost-effective institution to enable success

- Align civil service and contractor workforce with NASA and KSC goals and plans
- Continue the transformation of institutional facilities and infrastructure to support future needs
- Continue the transformation of technical capabilities/services required to support future NASA and multi-use programs
- Establish a model sustainability program


Goal 5: Inspire, engage, and educate through enriching programs, internships, and partnerships

- Assure effective community involvement, partnerships, and STEM awareness
- Increase STEM student opportunities at KSC

HF Research/Commercial Crew/ SLS-Orion



Thanks to Trent.M.Smith@nasa.gov for providing Commercial Crew slides.



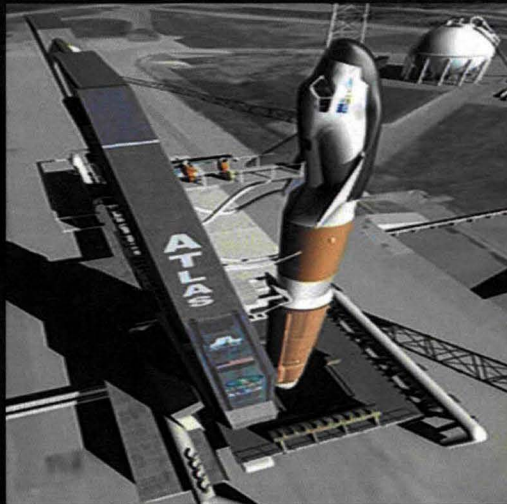
Goal 1: Ensure mission success by
enabling Government and commercial
access to space

Commercial

August 2012, NASA awarded CCIcap:

The Future of American

HUMAN SPACEFLIGHT



Dream Chaser/Atlas V



Dragon/Falcon 9



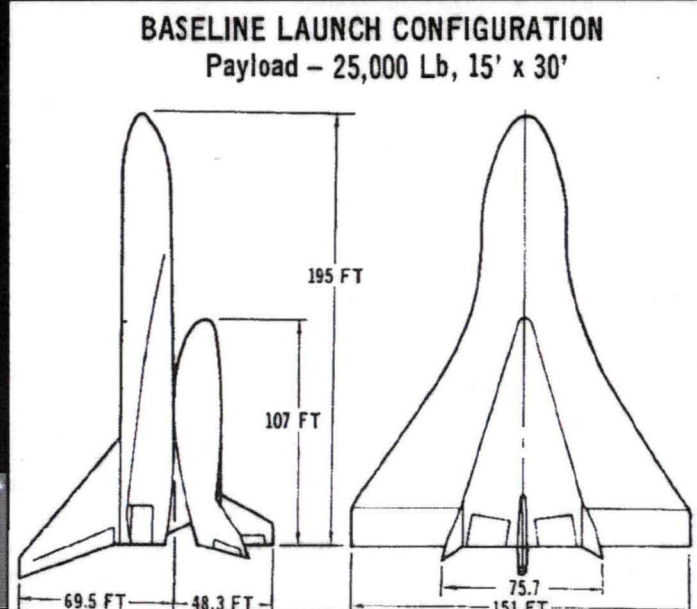
Boeing/Atlas V

CCiCap: A fully integrated system includes a spacecraft, launch vehicle, ground operations and mission control center.

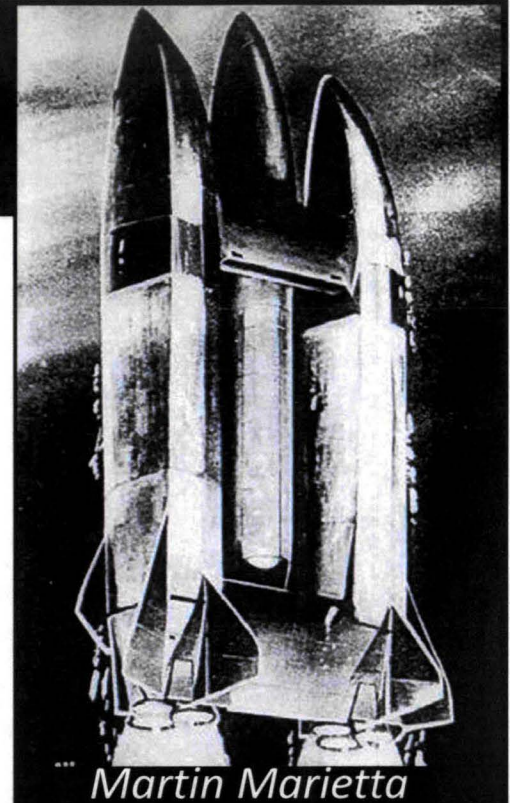
Thanks to Trent.M.Smith@nasa.gov Commercial Crew POC for providing slides.



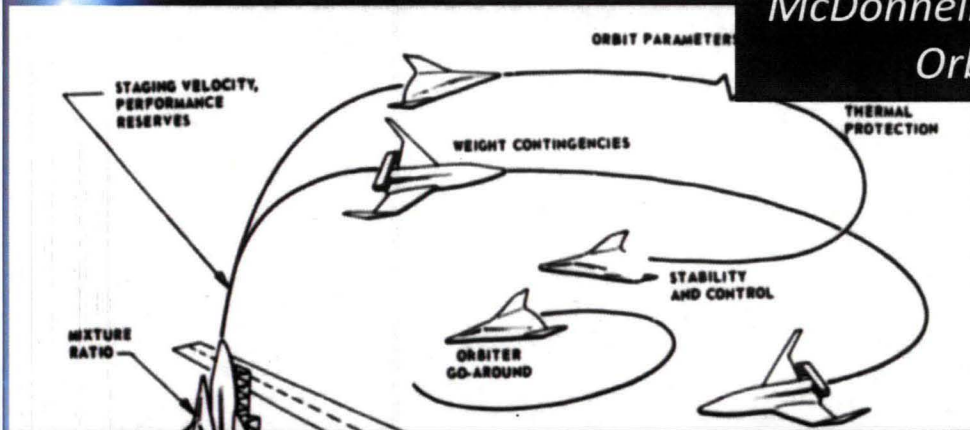
Space Shuttle Early Integrated Design Competition was key



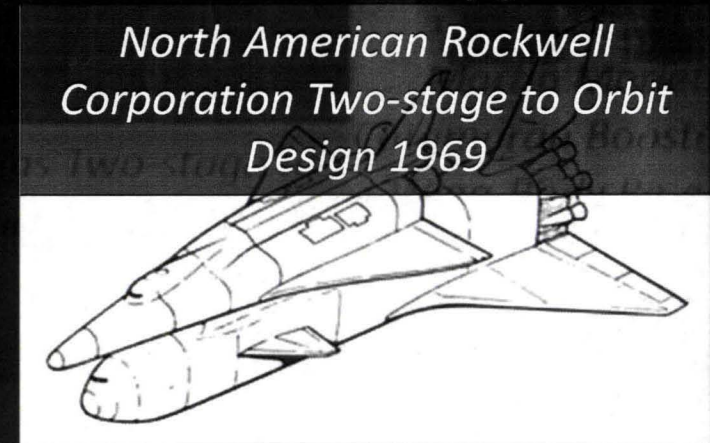
McDonnell Douglas Two-stage to
Orbit Design 1969



Catamaran Booster and
Wing-Body Re-entry
Configuration 1969



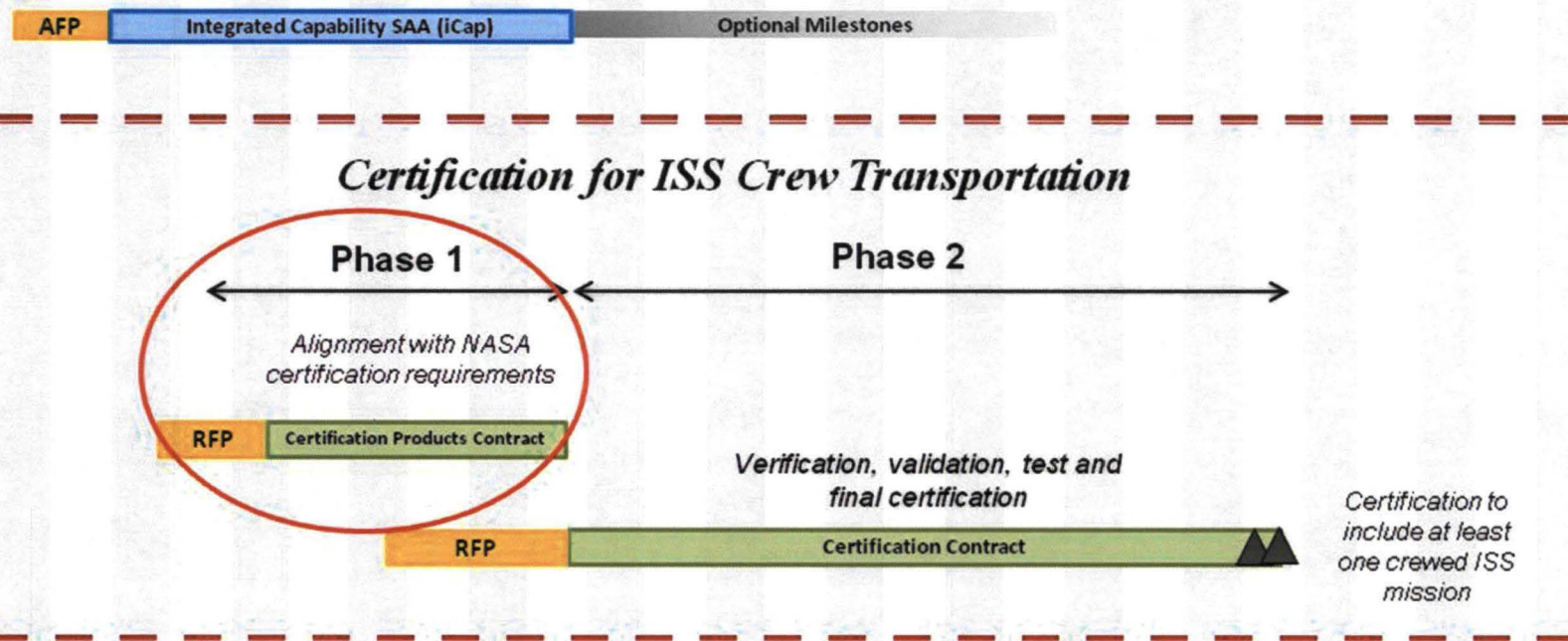
Lockheed Missiles & Space Company Two-stage
to Orbit Design 1969



Revised Acquisition Strategy (2012)

FY12	FY13	FY14	FY15	FY16	FY17	FY18

Commercial Crew Transportation System Development

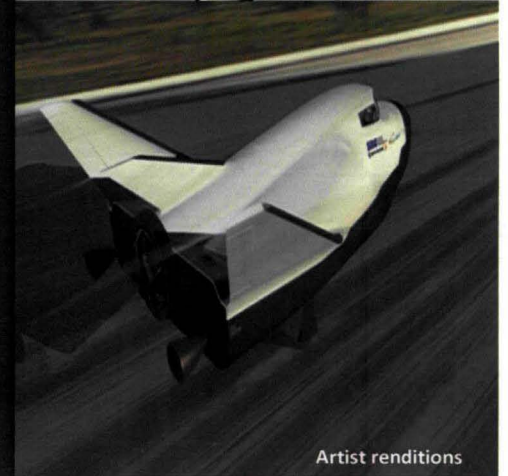
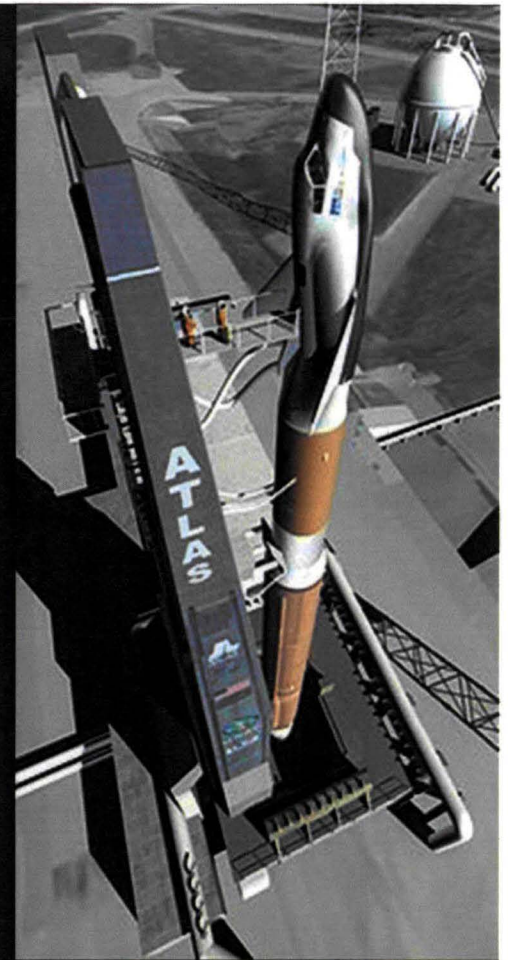


--Notional-- ISS Crew Transportation Services



Sierra Nevada Corporation

- Dream Chaser spacecraft is a reusable, piloted, lifting body.
 - Carries up to 7 crew members
 - Utilizes non-toxic propellants
 - **Primary Launch/Landing Site: Florida**
 - Ability to abort to a runway landing
- **Atlas V launch vehicle**
- **Testing:**
 - Engineering Test Article Flight(s)
 - Wind Tunnel Risk Reduction
 - Spacecraft Subsystem Risk Reduction
 - Main Propulsion Risk Reduction
 - Reaction Control System Risk Reduction

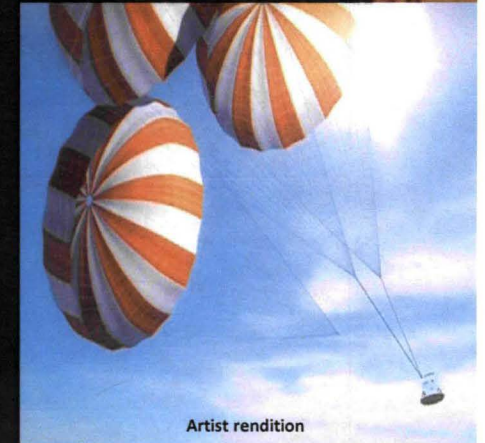


Artist renditions

Space Exploration Technologies Corporation

- Spacecraft uses a crewed version of the SpaceX Dragon capsule
 - Carries up to 7 crew members
 - **Primary Launch Site: Florida**
 - Primary Landing Site: "On land" landing
 - **Upgraded Falcon 9 launch vehicle**
- Flight tests:
 - Pad Abort (SLC 40 and last quarter of 2013)
 - In-Flight Abort (SLC 40 and 2nd quarter of 2014)

Picture of Falcon 9 rocket on launch pad in Florida



Artist rendition

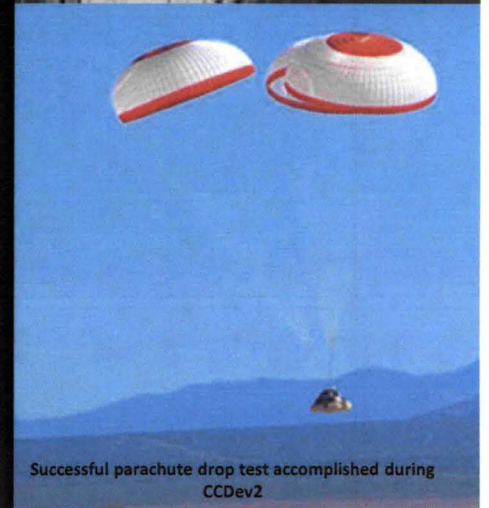
The Boeing Company

- CST-100 spacecraft is a reusable capsule design
 - Carries up to 7 crew members
 - **Primary Launch Site: Florida**
 - Primary Landing Site: "On Land" landing
- **Atlas V launch vehicle**

Testing:

- Integrated Stack Force & Moment Wind Tunnel
- Dual Engine Centaur Development
- Orbital Maneuvering & Attitude Control Engine Development
- Mission Control Center Interface Demonstration
- Emergency Detection System Standalone
- Avionics SW Integration Lab Multi-String Demonstration
- Pilot-in-the-Loop Demonstration

Artist rendition of CST-100 and Atlas V on the launch pad



Successful parachute drop test accomplished during CCDev2

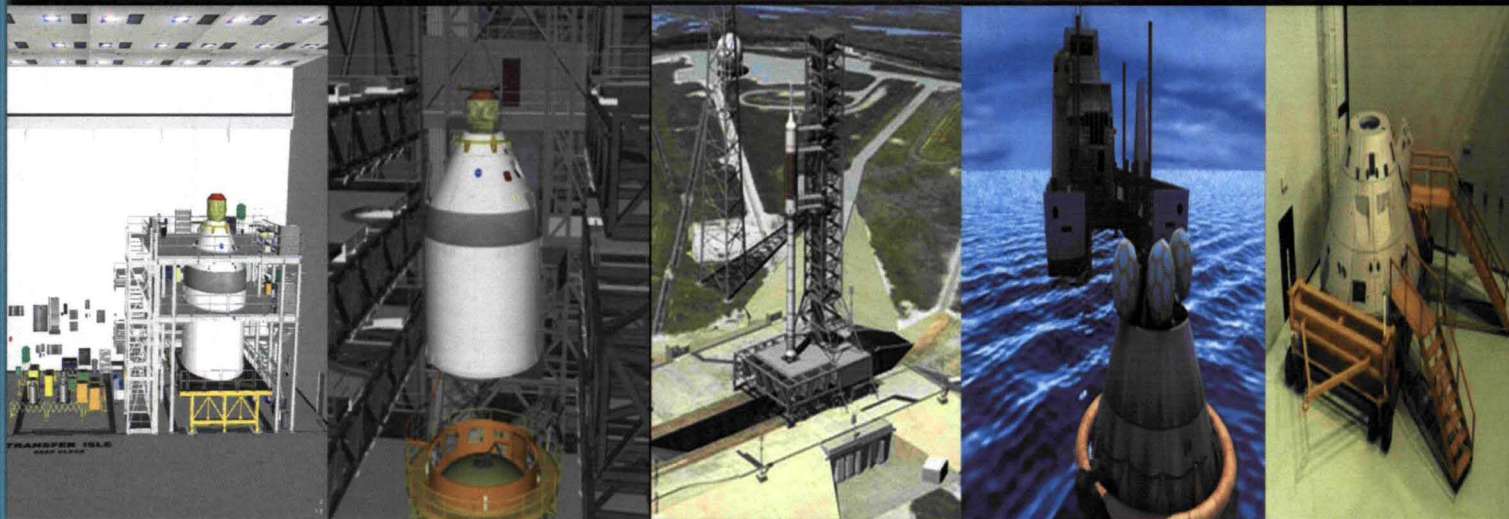


Goal 1: Ensure mission success by
enabling **Government** and commercial
access to space

Orion / Multi Purpose Crew Vehicle (MPCV)

The Future of American

HUMAN SPACEFLIGHT



MPPF

VAB

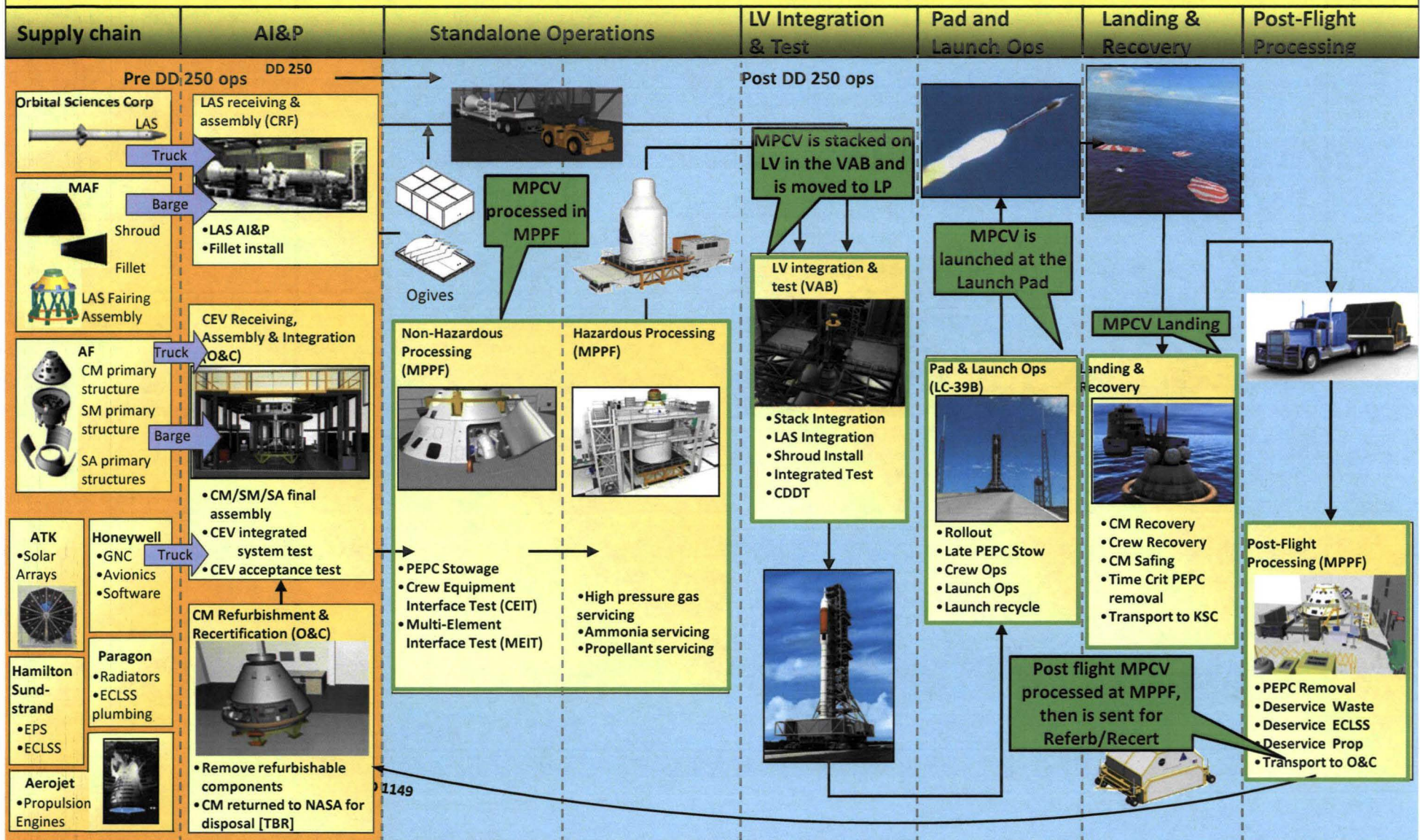
PAD

REC

O&C

Thanks to Gary.F.Letchworth@nasa.gov & Roland.Schlierf-1@nasa.gov for providing MPCV slides.

Orion Ground Operations Flow

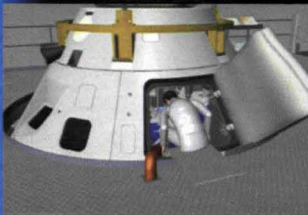


MPPF – Non-Hazardous Ops

From O&C



To
MPPF



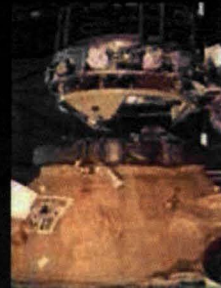
Initial Provisions Stowage

- T-0 connection (power, control, data, purge)
- Time critical PEPC fit checks



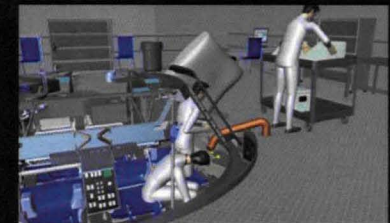
Crew Equipment Interface Testing - CEIT

- Verify flight crew to Orion interfaces



Multi Element Interface Test - MEIT

- Verify Orion interfaces to other flight elements (ISS, Altair, etc.)
- Not for every flow

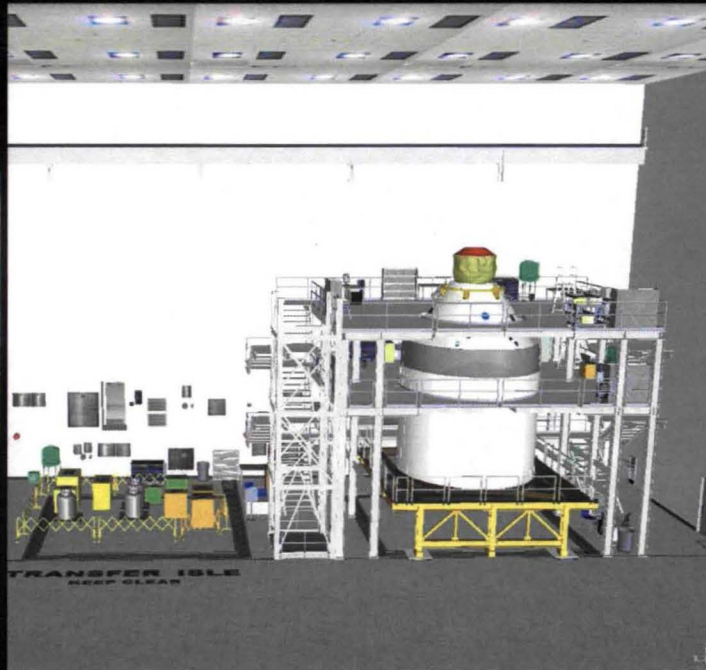


Cargo Stowage and Integration

- PEPC stowage
- Potable water service and sample

MPPF – Hazardous Ops

At MPPF



To VAB



High Pressure Gas Servicing
GO₂, GN₂, GHe,

Ammonia Servicing
NH₃

Hypergolic Servicing
N₂O₄, MMH, N₂H₄

VAB - Launch Vehicle Integration Ops

Short Stack From MPPF



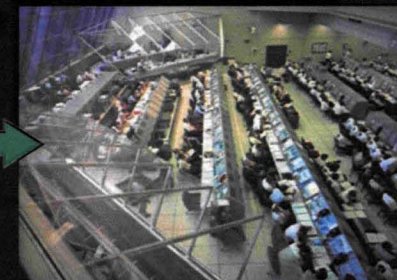
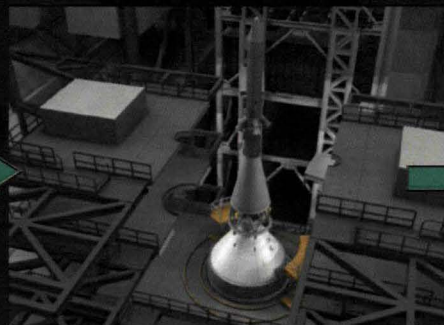
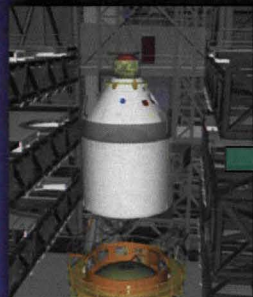
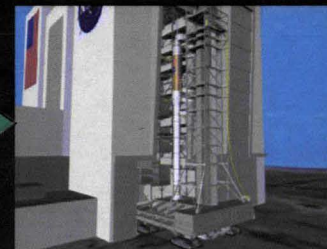
LAS from CRF



VAB



Rollout to Pad



**Lift & Mate
Short Stack to CLV**

- Lift and mechanical mate with the upper stage IU
- Electrical mates
- Connect T-0
- Initiate Purge
- Perform I/F test (powered)

LAS Integration to CM

- Lift and mechanical mate LAS to CM
- LAS to CM Electrical mate
- LAS Interface Test & S&A rotation test (powered)
- Ordnance mate

Ogive Installation

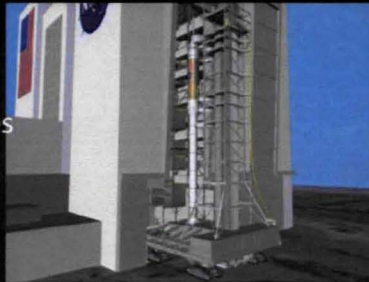
- Install Ogive Panels (4)
- Closeout TPS
- Establish internal access (white room)

Integrated Testing

- Vehicle power up & health status
- IVT (including RF testing)
- Potable water sample
- Countdown Demo Test (CDDT)

Pad and Launch Ops

- Rollout to Pad with active purge
- Connect Pad to ML interfaces
- Establish External access (CAA & SM VAA)

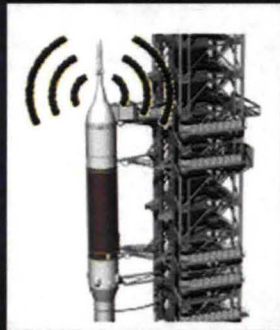


From VAB



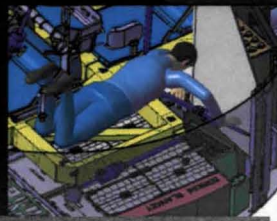
LC-39B

Mission Ops



Communications Testing

- Orion Power-up
- Pad IVT
- Comm. End-to-End Testing
 - Uses antennas on LAS



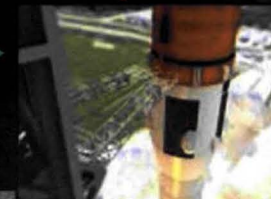
Late Stowage and Final Ordnance

- Late PEPC Stowage
- CM, SM Ordnance Ops
- LAS arm inhibit removals (S&A pins)



Crew Operations

- Crew Ingress
- Hatch Seal Leak Checks
- Cabin Leak Checks
- White Room seal retract
- CAA retract



Launch Readiness Through T-0

- Final countdown and Launch

Landing & Recovery Ops



From Flight Ops



To MPPF



Water Landing



Water Recovery



Transportation

- Location data transmitted to MCC, relayed to recovery crew
- Auto-safing of pyros & fluid systems performed and status provided to MCC
- CM beacon transmits vehicle location to recovery crew

- Remove CM from water (crew on-board)
- Crew egress after CM secured on ship
- Manual Pyro Safing
- Remove Time Critical PEPC

- Install lifting device on CM
- Transfer CM to transporter on dock
- Prepare for over-the-road transportation
 - Transfer CM transporter to trailer
- Transported to MPPF at KSC

Post Flight De-servicing

From Landing Site



MPPF



O&C



De-service Preps

Remove CM transporter from over the road trailer
Clean CM & transporter
Move CM transporter in MPPF airlock
Move CM & transporter into High bay for de-servicing



Remove PEPC

- Remove seats
- Remove non-time critical PEPC
- Remove Human Waste
- Flush and Drain Urine system and decontaminate WMS



De-servicing

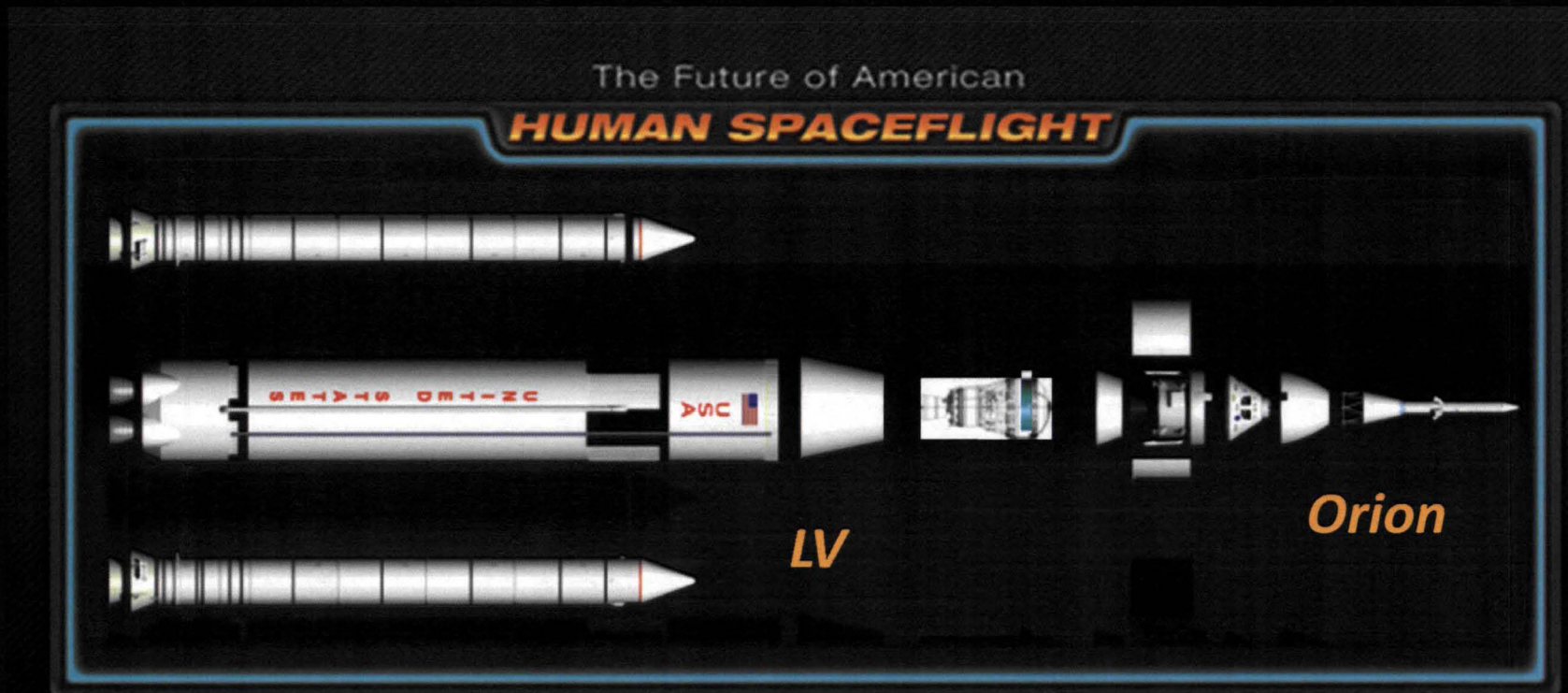
- Data Retrieval if required
- De-service Ammonia system
- De-service ECLSS gases
- Discrete Propulsion system Power-up
- Decontaminate Hydrazine system



Return to O&C

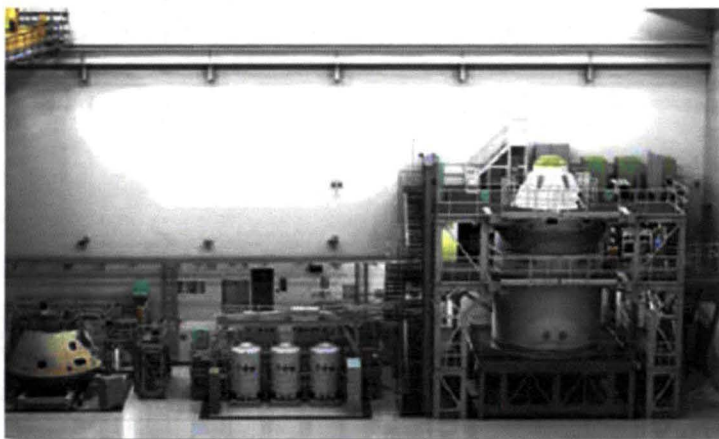
- Move from de-servicing area
- Configure for Transport
- Transport CM and components back to O&C

Orion / SLS



Thanks to for providing slides.

Offline Processing & Infrastructure (OPI)



Spacecraft Offline Processing



Landing & Recovery



Launch Vehicle Offline Processing



Environmental & Infrastructure

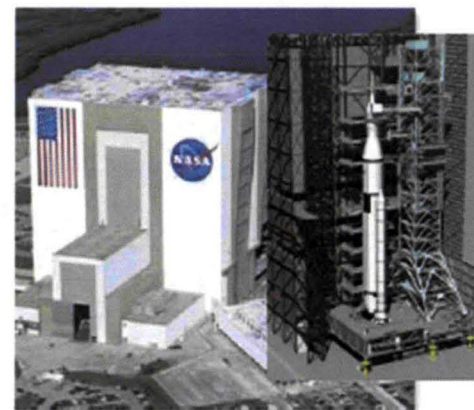
Vehicle Integration & Launch (VIL)



**Mobile Launcher –
Orion and SLS access
and servicing**



**Pad - LC-39B
Launch Operations**

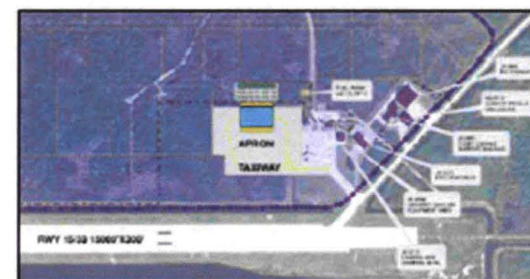


**VAB – SLS and Orion
Integration and Check-out
Operations**



**Crawler Transporter – ML,
MLP and Integrated Stack
move operations**

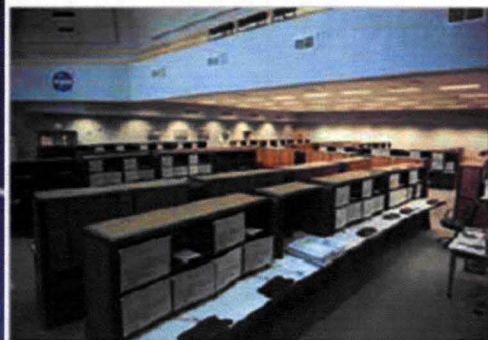
VIL Capabilities



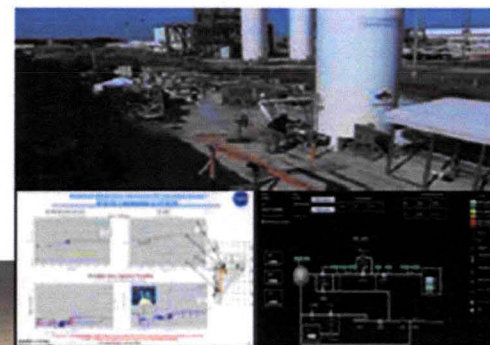
**Small Class Vehicle -
Planning and Studies***

*SCV not included in GSDO SRR/SDR

Command Control Communications & Range (C3R)



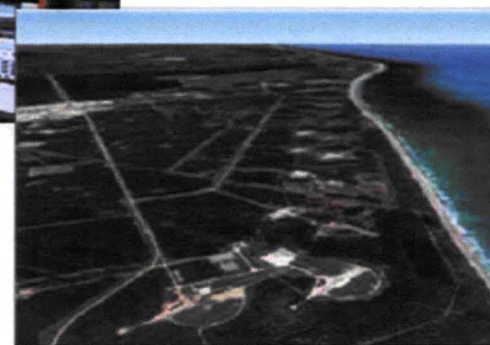
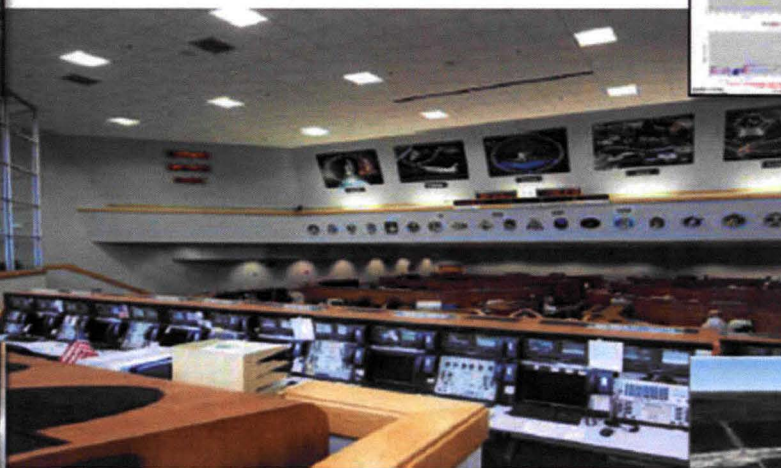
End to End
Command & Control



Advanced Ground Systems
Maintenance (AGSM)*



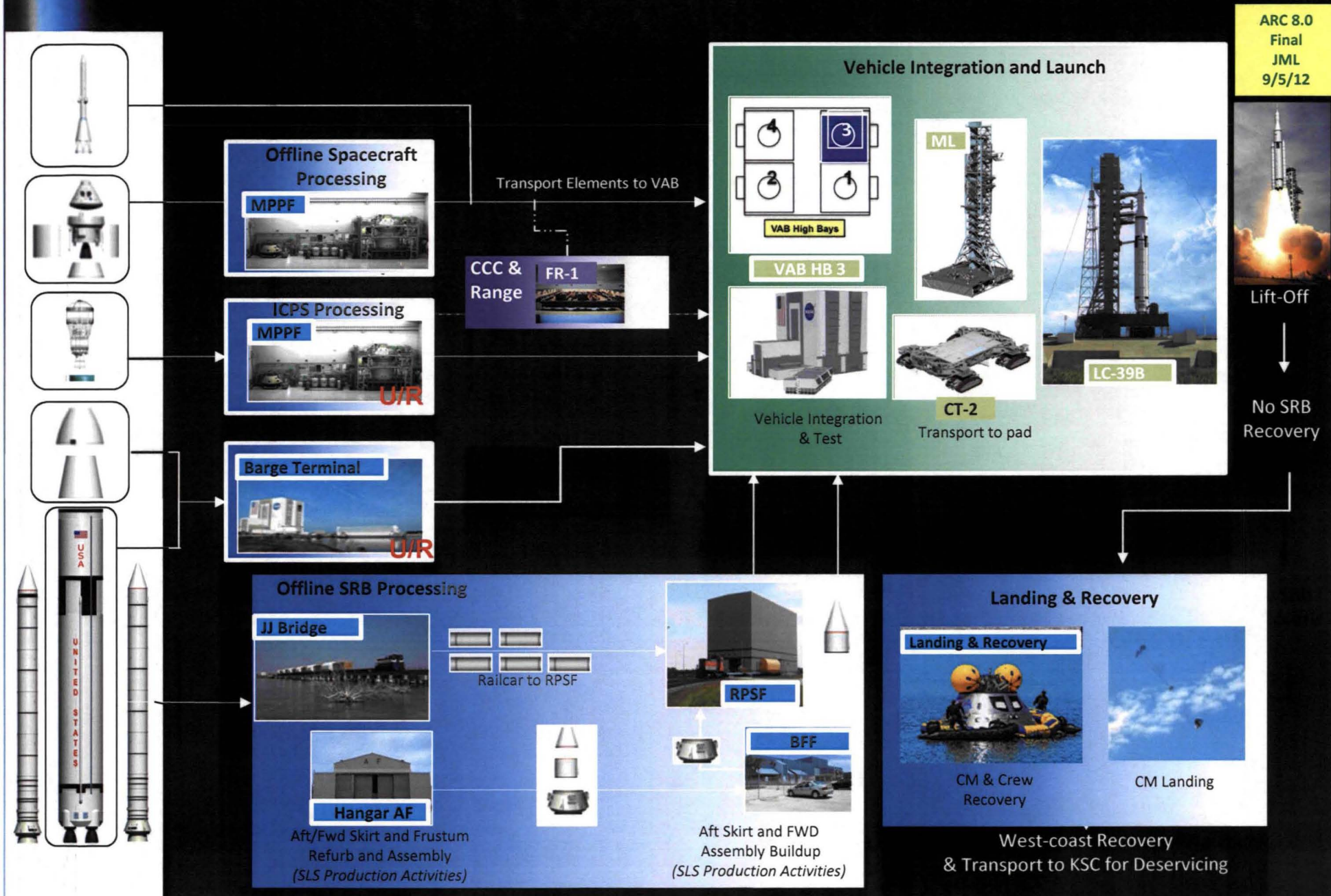
Communications Systems



Range Systems*

C3R Capabilities

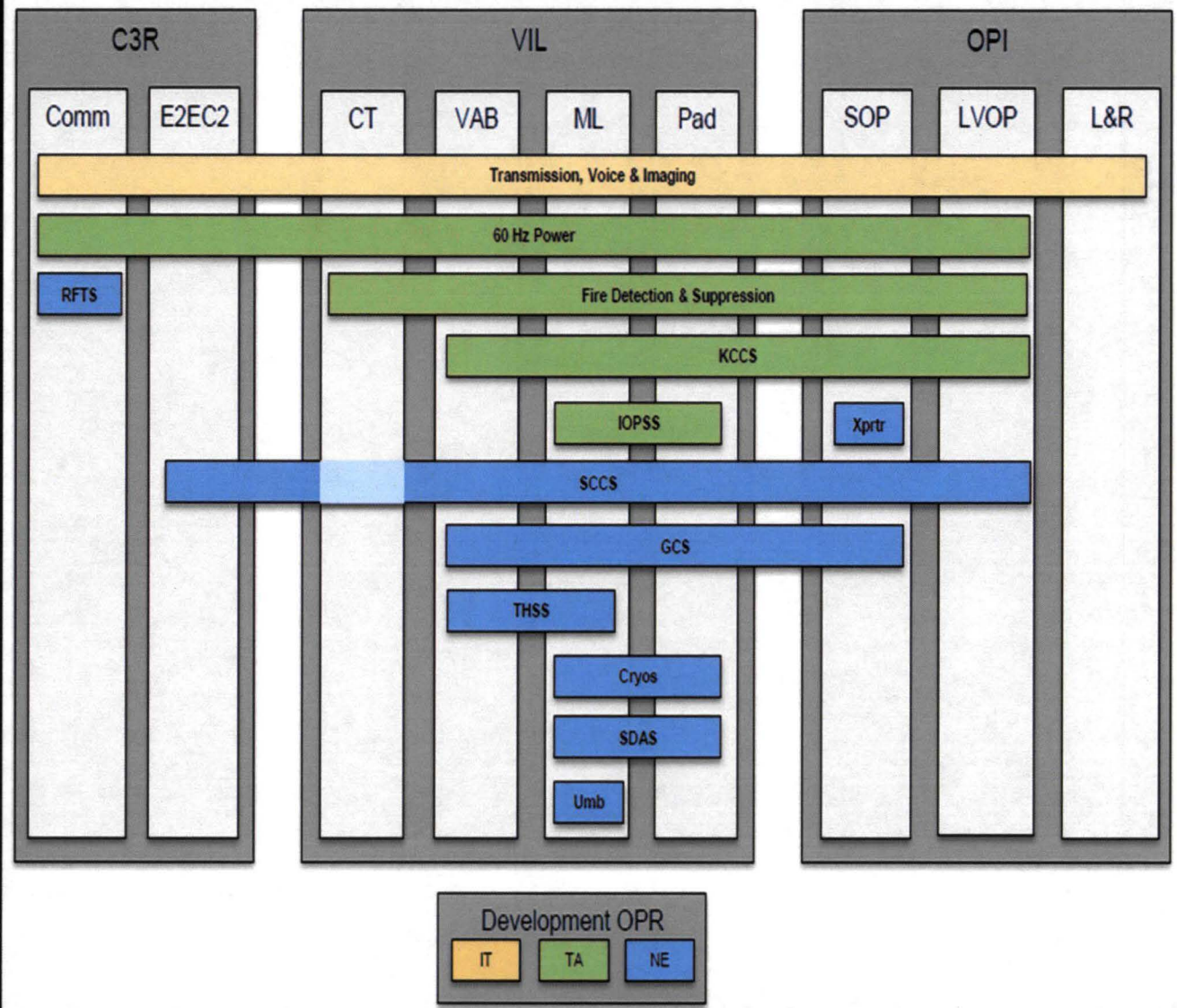
Orion/SLS Concept of Operations



Subsystem-EIT-IPT Integration

GSDO MSL has 70 Subsystems identified and some cross multiple EITs/IPTs .

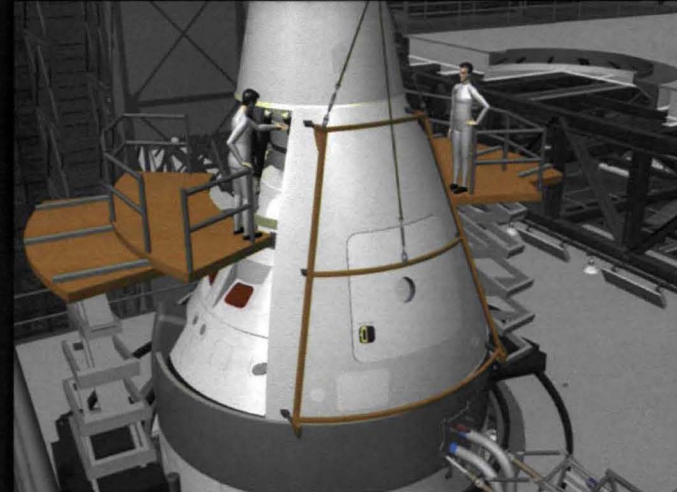
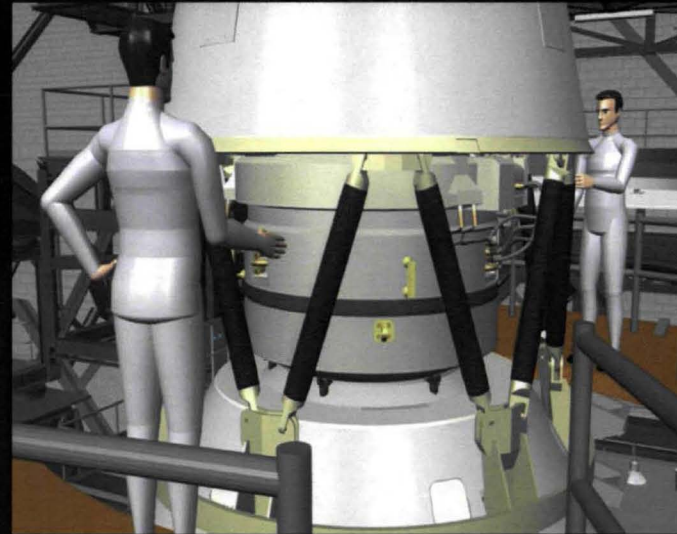
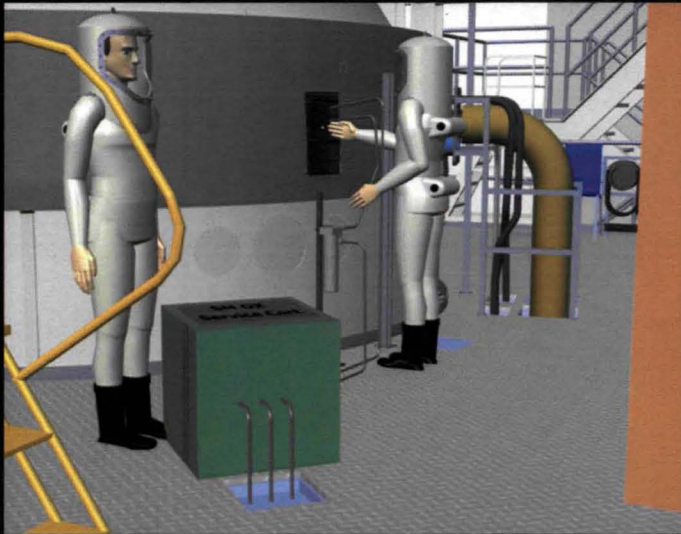
Crosscutting Subsystems will be designed end to end per the Institutional design processes



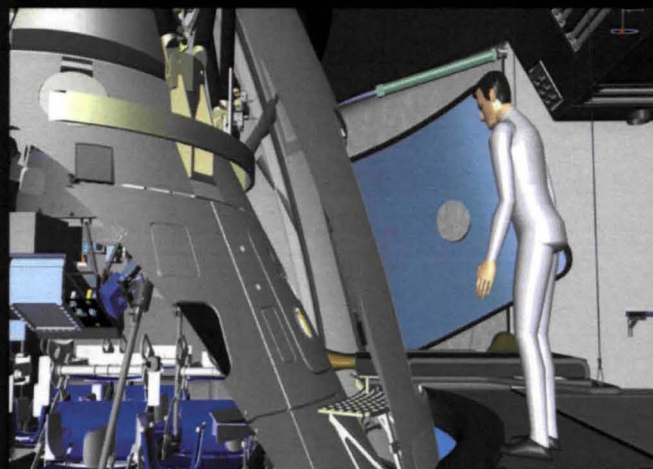
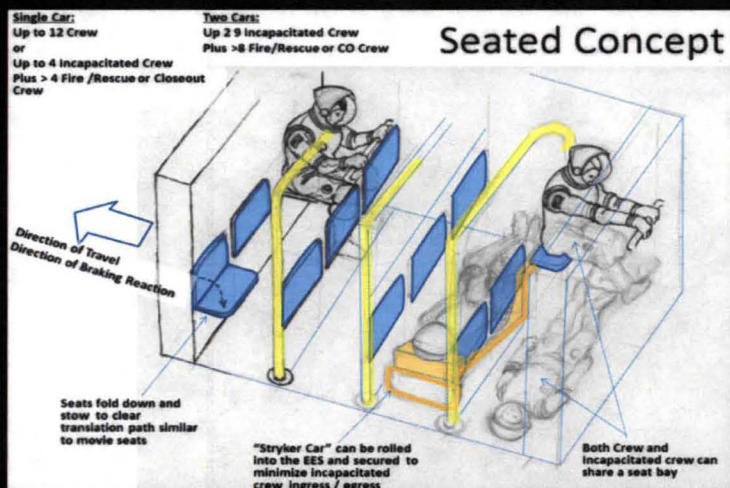
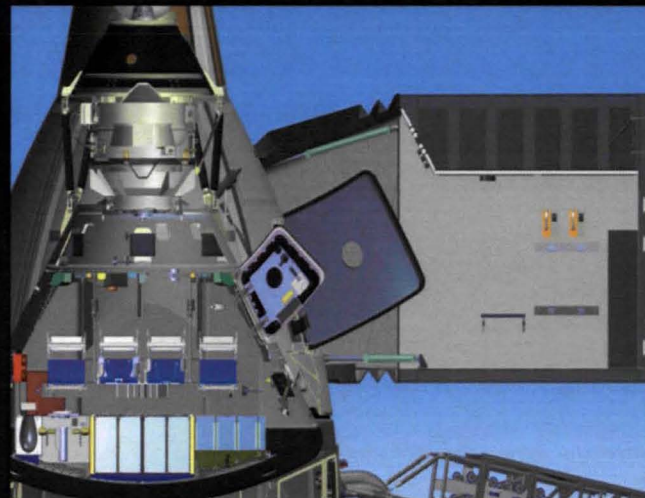
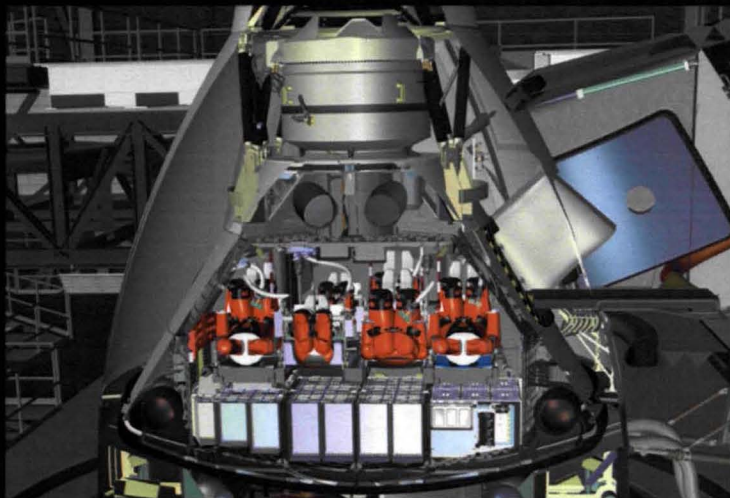
Current GSE Human Systems Engineering Analysis Directions

- Orion Handing and Access
- Crew Access Arm Ingress/Egress
- Installing/Removing the GSE side umbilical plates
- CAA Basement
- SLS Access Locations
- ICPS SCAPE Operations
- LAS
- VAB CAA interference issue with the TMLs
- Core stage Linear Shaped Charge
- Aligning/installing Core Stage to SRB
- ICPS Sling Removal

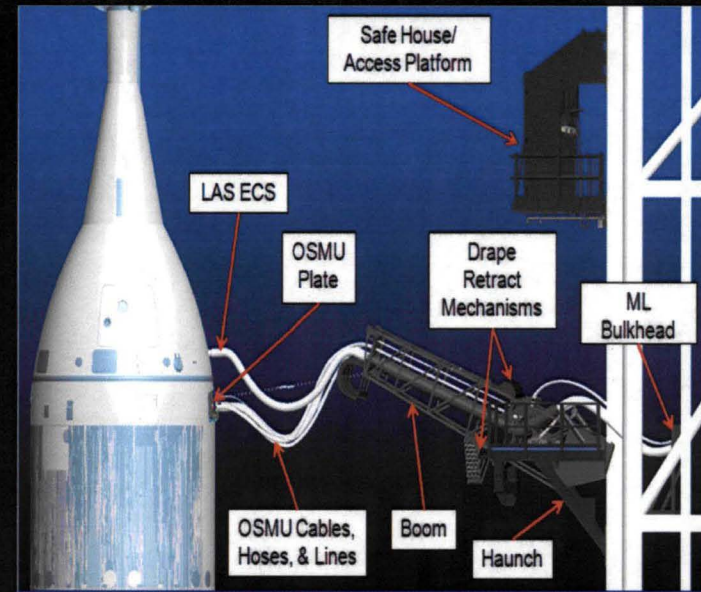
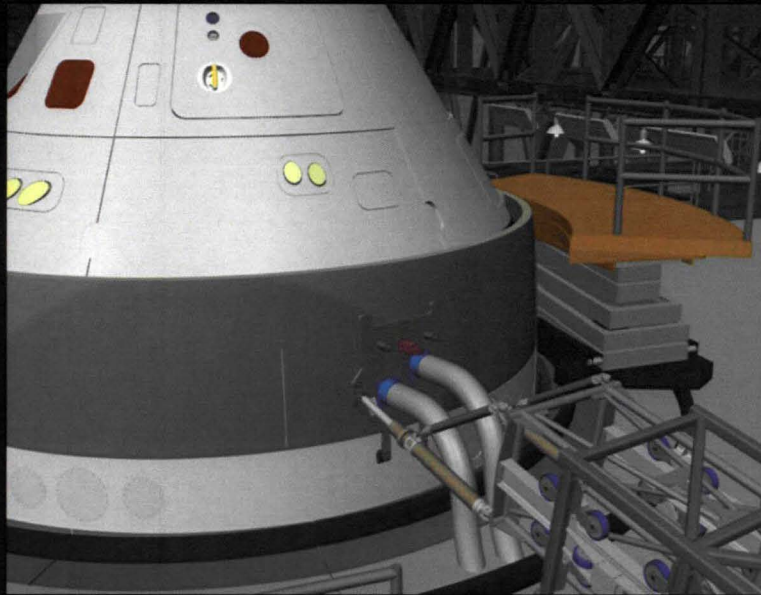
Orion Handing and Access



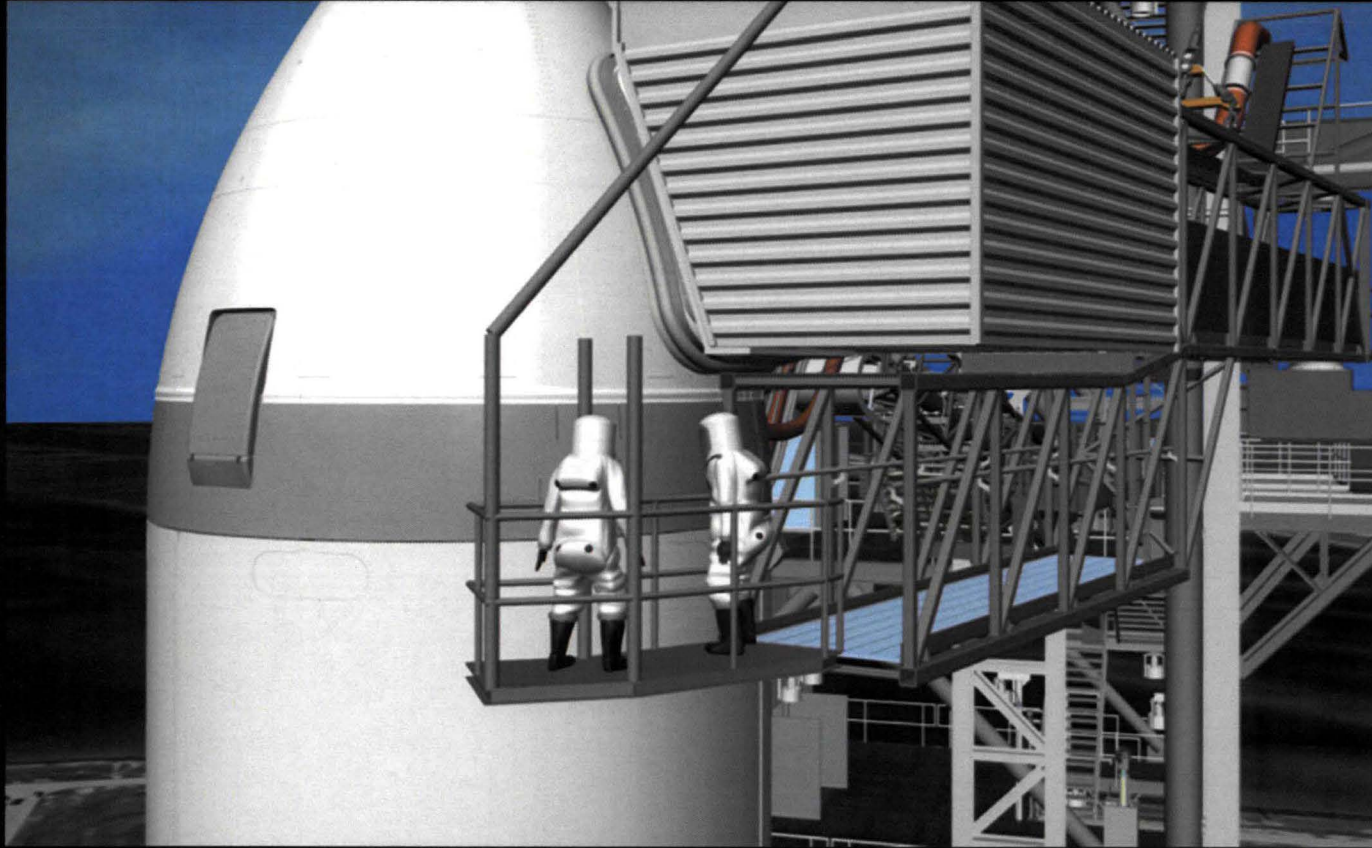
Crew Access Arm Ingress/Egress



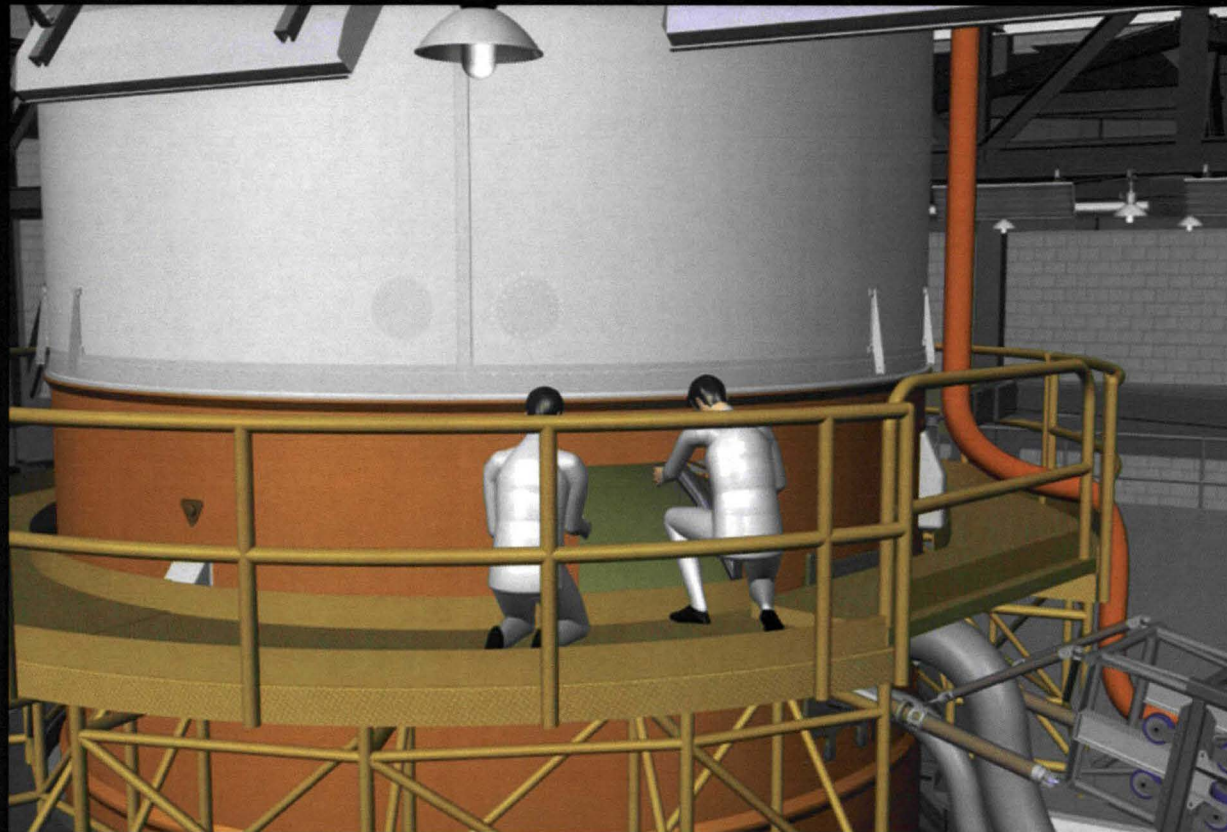
Installing/Removing the GSE side umbilical plates



CAA Basement



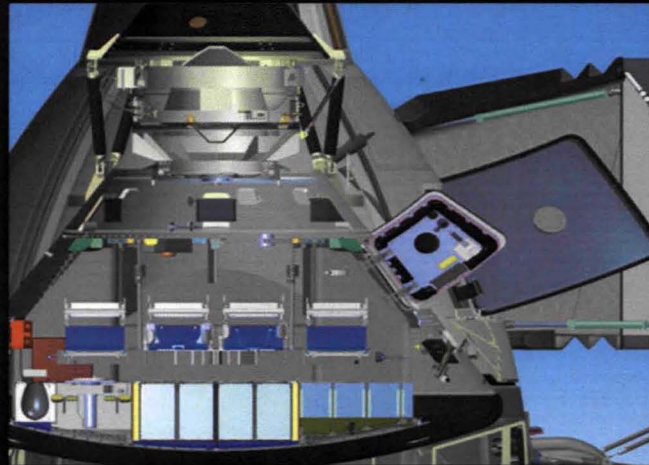
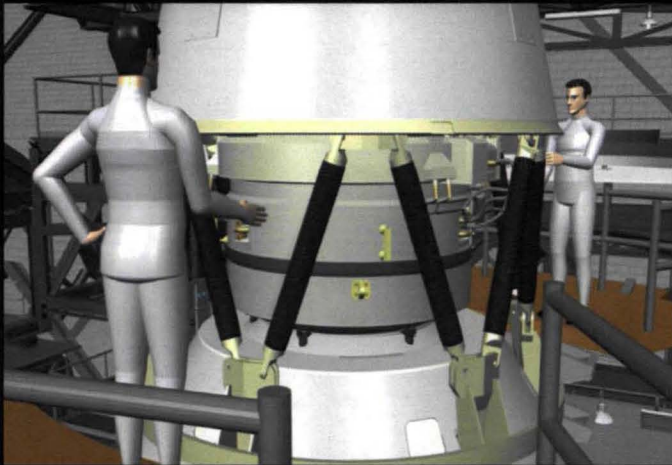
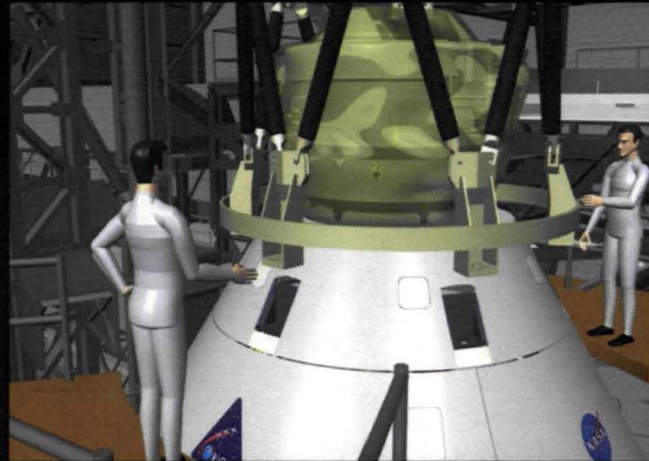
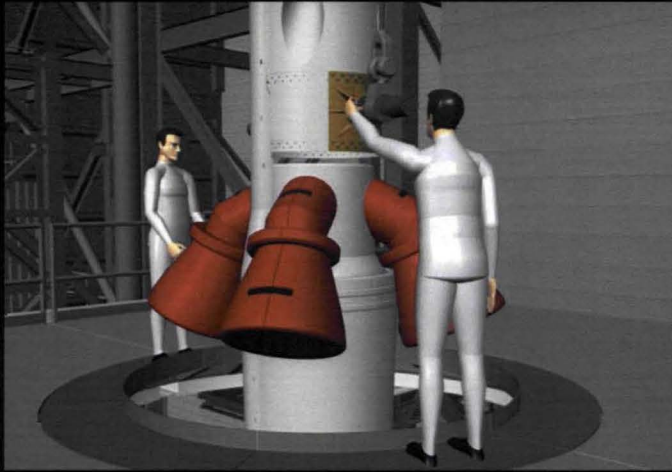
SLS Access Locations



ICPS SCAPE Operations



LAS



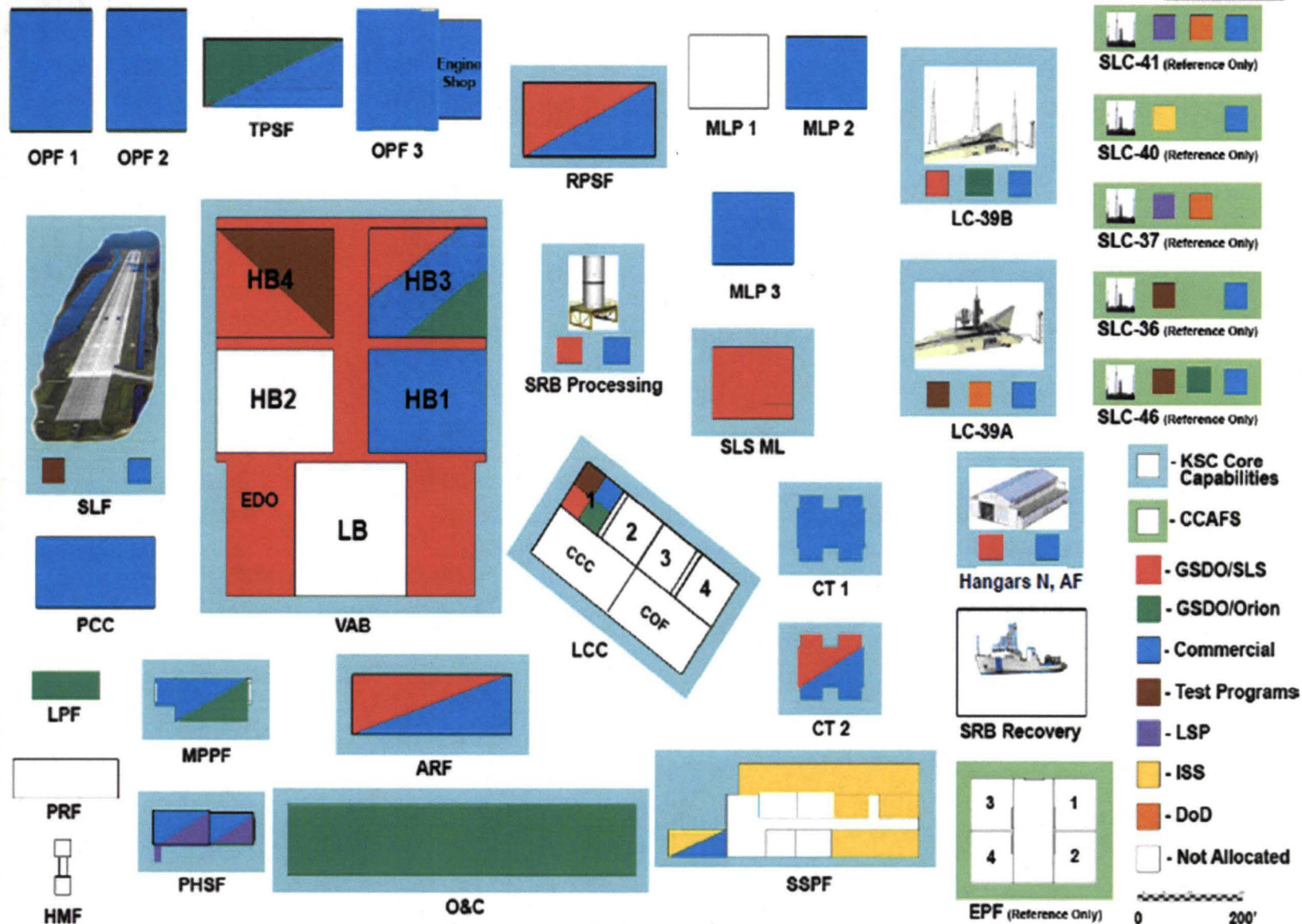
Goal 2: Develop, operate, and sustain a robust launch and payload processing complex for all providers

a. Convert the KSC launch and payload processing complex into a multi-user capability


ARC 7.0 Final Point of Departure Review

Final PoD Integrated Program Architectures (PA) View - 1

ARC 7.0 Final
RPC 3/15/12



Architectures include programs and institutional capabilities; SLS/Orion assets are limited to single string.



Goal 3: Conduct research and develop
technology (R&T) representative of
KSC expertise to enable NASA
mission success

KSC HF Research Directions

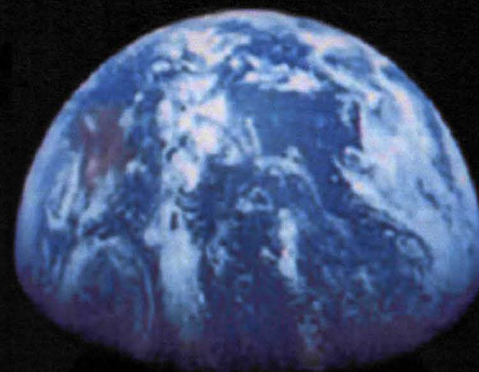
- *3D CAD-Human and Hardware Collaborative Engineering* is a study to compare the effectiveness of using a 3D CAD/collaborative environment versus existing methods used in Design Engineering for hardware developed for human operators.
- *Primitive Motions for Developing Human Hardware Models* is the development of the “Primitive Motions” library based on motion capture of actual humans. These motions can then be used by modelers to infuse the human motions into CAD models to verify human factors requirements.
- *Collaborative Human Immersive Virtual Environment (CHIVE)* is the development of a collaborative human immersive virtual environment for CAD developers, Engineers, Technicians, partners, and program integration entities. The CHIVE will have the ability to connect multiple NASA centers and partners simultaneously to promote optimal concurrent engineering collaborations.

KSC HF Research Directions

- ***Human-In-Loop Performance Modeling & Cognitive Simulation Integration*** is the development of human performance models that integrate cognitive with biomechanical data and validated natural human motions and tendencies.
- ***Virtual Mentor Training*** is the development and study of a virtual mentor trainer.
- ***Virtual Environments for Long Duration Missions***: It is well known that one of the greatest challenges to overcome in long duration missions is the psychological factor. To counteract the loneliness of long missions, virtual scenarios will be developed of common daily activities.

"History is a relentless master. It has no present, only the past
rushing into the future. To try to hold fast is to be swept aside."

~ John F. Kennedy



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